

First Name: Eva-Maria
Last Name: Brunner
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Homework Title: PI (MPI Programm)

Problem:

This exercise presents a simple program to determine the value of pi. The algorithm suggested here is chosen for its simplicity. The method evaluates the integral of $\frac{4}{1+x^2}$ between $-\frac{1}{2}$ and $\frac{1}{2}$. The method is simple: the integral is approximated by a sum of n intervals; the approximation to the integral in each interval is $\frac{1}{n} \cdot \frac{4}{1+x^2}$. The master process (rank 0) asks the user for the number of intervals; the master should then broadcast this number to all of the other processes. Each process then adds up every n'th interval ($x = \frac{-1}{2} + \frac{rank}{n}, \frac{-1}{2} + \frac{rank}{n} + \frac{size}{n}$). Finally, the sums computed by each process are added together using a reduction.

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Solution:

```
#include "mpi.h" /* provides basic MPI definitions and types */
#include <math.h> /* provides basic mathematical functions*/

int main(argc,argv)
int argc;
char *argv[];
{
    int done = 0, n, myid, numprocs, i;
    /*true value of pi (rounded) for comparision*/
    double PI25DT = 3.141592653589793238462643;
    /*instanz variable*/
    double mypi, pi, h, sum, x;

    /* starts MPI*/
    MPI_Init(&argc,&argv);
    /*the number of all processors are written into the variable numprocs*/
    MPI_Comm_size(MPI_COMM_WORLD,&numprocs);
    /* determines the processor id for each processor (from 0 to size-1)*/
    MPI_Comm_rank(MPI_COMM_WORLD,&myid);

    while (!done)
    {
        /* the process with the id 0 starts and asks the user for input*/
        if (myid == 0) {
            printf("Enter the number of intervals: (0 quits) ");
            scanf("%d",&n);
        }
        /* the process with the id 0 sends the same data to all other prozesses,
        the data is a single MPI_INT variable namely n*/
        MPI_Bcast(&n, 1, MPI_INT, 0, MPI_COMM_WORLD);
        if (n == 0) break;
        /* determines the length of a subintervall*/
        h = 1.0 / (double) n;
        sum = 0.0;
        /* the main part of the programm where the integral for all x is computed*/
        for (i = myid + 1; i <= n; i += numprocs) {
            /*current interior point*/
            x = h * ((double)i - 0.5);
            /* each result of the subintervall approximation is added*/
            sum += 4.0 / (1.0 + x*x);
        }
        /* mypi is a part of pi computed by the current process*/
        mypi = h * sum;
        /* combines mypi from all processes using MPI_SUM*/
        MPI_Reduce(&mypi, &pi, 1, MPI_DOUBLE, MPI_SUM, 0,
            MPI_COMM_WORLD);
        /*the root process (with the id 0) compares the computed result with the true
        value of n*/
        if (myid == 0)
            printf("pi is approximately %.16f, Error is %.16f\n",
                pi, fabs(pi - PI25DT));
    }
    /* Ends MPI */
    MPI_Finalize();
    return 0;
}
```

Results:

We will change the problem described above a little because

$$\int_a^b \frac{4}{1+x^2} = 4 \int_a^b \frac{1}{1+x^2} = 4(\arctan b - \arctan a) \text{ should be equal to } \pi.$$

The boundaries $-\frac{1}{2}$ and $\frac{1}{2}$ don't fit the requirements because

$$\int_{-0.5}^{0.5} \frac{4}{1+x^2} = 4(\arctan 1 - \arctan 0) \neq \pi.$$

We take the boundaries 0 and 1 which give an accurate result:

$$\int_0^1 \frac{4}{1+x^2} = 4(\arctan 1 - \arctan 0) = 4\left(\frac{\pi}{4} + 0\right) = \pi.$$

So it is easier to describe the interprocess communication.

Interprocess communication:

To illustrate how the interprocess communication works we will describe it with reference to a division of $[0,1]$ in 4 subintervals ($n = 4$) $[0, \frac{1}{4}]$, $[\frac{1}{4}, \frac{2}{4}]$, $[\frac{2}{4}, \frac{3}{4}]$, $[\frac{3}{4}, 1]$ and compute the interior point as

following ($x = h * ((double) i)$). We assume that the number of processes is 3.

So the first (root, $id = 0$) process approximates the first and last interval

$$mypi = h \cdot \sum = \left(\frac{1}{4}\right) \cdot \frac{4}{1+\left(\frac{1}{4}\right)^2} = \frac{1}{1+\frac{1}{16}} = \frac{16}{17}, \quad \frac{1}{4} \cdot \frac{4}{1+1^2} = \frac{1}{2}$$

the second process ($id = 1$) approximates the second interval $mypi = \frac{1}{4} \cdot \frac{4}{1+\left(\frac{2}{4}\right)^2} = \frac{1}{1+\frac{4}{16}} = \frac{4}{5}$ and the

third process ($id = 2$) the third interval $mypi = \frac{1}{4} \cdot \frac{4}{1+\left(\frac{3}{4}\right)^2} = \frac{1}{1+\frac{9}{16}} = \frac{16}{25}$.

In this case π is $\frac{16}{17} + \frac{1}{2} + \frac{4}{5} + \frac{16}{25} = \frac{2449}{850} = 2,881176470$ which is 91,7% correct.

The tutorial computed the interior point with $x = h * ((double)i - 0.5)$ contrary to our example above where we took $x = h * ((double) i)$. We choose $x = h * ((double) i)$ for the illustration because the solution it produces converges much faster to π

Taking $x = h * ((double)i - 0.5)$ and $n = 4$ we get: $\frac{4}{5} + \frac{4}{13} + \frac{4}{29} + \frac{4}{53} = 1.32109504029$

which is only 42,05% correct..